

FUNCTION GENERATOR

Design by H. Bonekamp

A generator is described that, based on the MAX038, provides triangle, sawtooth, sine, rectangular and pulse waveforms.

The MAX038, on which the present generator is based, is an integrated, high-frequency, precision function generator whose output frequency can be controlled over a frequency range of 0.1 Hz to 20 MHz by an internal 2.5 V bandgap voltage reference and an external resistor and capacitor. Its duty factor can be varied over a wide range by applying a ± 2.3 V control signal, facilitating pulse-width modulation and the generation of sawtooth waveforms. Frequency modulation and frequency sweeping are achieved in the same way. The duty factor and frequency controls are independent.

Circuit description

The circuit diagram of the generator proper is shown in **Fig. 1** and that of the liquid crystal display, LCD, in **Fig. 2**.

The frequency of the MAX038, IC₁, is determined by C₁–C₇ which are linked to pin 5 via S_{1a}. The highest frequency is governed by C₅–C₇, an arrangement that eliminates the effect of parasitic capacitances (about 20 pF). Switch section S_{1b} sets the decimal point on the display.

The waveform is selected with S₂, one of whose sections (a) is linked to selection input pins 3 and 4 of IC₁. The second section (b) is used to set the duty factor and symmetry of relevant output signals (triangle, sine and rectangular).

The symmetry is set with an auxiliary voltage derived from the reference potential, $U_{ref} = 2.5$ V, which is generated internally by IC₁. The duty factor must be adjusted with a symmetrical reference voltage, which is obtained by inverting U_{ref} in IC_{3a}, that is, amplified by -1 . The op amp is stabilized by an RC network. The control range of P₁ then extends from $-U_{ref}$ to $+U_{ref}$.

The signal at the wiper of P₁ is applied to duty factor adjust pin 7 of IC₁ via IC_{2b} when S₂ is set to position sine, triangle or rectangular. In positions triangle and pulse, the potential at pin 7 is set with P₂. Although this potentiometer also has a control range of $-U_{ref}$ to $+U_{ref}$, this is reduced to about 40%. This diminution is required since all control inputs, with the exception of sweep, are normalized to a range based on a control voltage of ± 1 V.

The signal frequency can be varied via voltage-controlled frequency adjust input pin 8 and via current-controlled frequency control current input pin 10 of IC₁.

A voltage is applied to pin 8 when an external signal is to provide frequency modulation. The control voltage, taken from K₄, is applied via S_{3a} to IC_{2a}, in which it is raised $\times 2.4$ to normalize it to ± 1 V.

With switch S₃ in position 1, the input at pin 10 of IC₁ enables the frequency to be set manually so that the generator can be used in the traditional way. Pin 8 is then low (via IC_{2a}). The current sunk via pin 10 varies between 16 μ A and 250 μ A.

With S₃ in position 3, the central frequency can be set with P₅, whereupon the frequency sweep around this frequency is arranged by a voltage at K₄.

With S₃ in position 2, op amp IC_{6b} raises the external sweep signal at K₄ $\times 7.5$, whereupon the signal is passed to IC_{6a} via S_{3b}. Op amp IC_{6a} is connected as a voltage follower, whose output is converted into a current to pin 10 of IC₁ by R₃₀. Here again, pin 8 is made low.

The output signal is available at OUT (pin 19) of IC₁. Since this is not sufficient, it is applied to buffer amplifier IC₄. This op amp has a slew rate of 1000 V μ s⁻¹ and a peak output current of 150 mA. It amplifies the output of IC₁ $\times 10$ and, at the same time, ensures correct compensation of the offset voltage (in conjunction with IC_{3b}). The output voltage at K₃ can be preset between 0.5 V_{pp} and 22 V_{pp}. Resistors R₂₂, R₂₃, R₂₄, and R₂₅ ensure an output impedance of 50 Ω , and at the same time that the output resistance can dissipate sufficient power.

The junction R₁₈–R₁₉–R₂₀ is at ground potential for a.c. via C₁₈, C₁₉ and C₂₀, but direct voltages at the output of IC_{3b} are applied to IC₄. Since IC₃ does not work well with a capacitive load, a compensating network, R₁₈–R₁₉–C₁₇ is provided at its pin 7. In this way, the offset of the output signal can be adjusted by ± 5 V.

The SYNC output (pin 14 of IC₁) is buffered by TTL gate IC_{5e} and then applied to K₁. The signal is at TTL level. The impedance at K₁ is 50 Ω .

All op amps in the circuit, in which signals at frequencies up to 100 MHz can occur, are decoupled extensively.

The power supply is straightforward and traditional. The rectified symmetri-



Brief specification

Output waveform: sine, triangle, pulse, rectangular, sawtooth
 Rectangular wave: $t_r, t_f \ll 15$ ns
 Duty factor: variable 15–85%
 Sine wave: frequency range: 10 Hz–10 MHz;
 THD $\ll 1\%$
 Number of ranges: 6
 Frequency stability: $df/f \ll 0.1\%$
 Output level (sync): TTL
 Output level (analogue): 20 V peak to peak
 Offset compensation: ± 5 V
 Display: 4½ digit
 FM modulation: $f_o \pm 70\%$
 FM sensitivity: ± 1 V
 FM bandwidth: 2 MHz ($R_{in} = 100$ k Ω)
 Sweep range: 25:1
 Sweep sensitivity: 0–1 V
 Sweep bandwidth: 10 kHz ($R_{in} = 100$ k Ω)

cal voltage is regulated by IC₇ and IC₈ to ± 15 V and by IC₉ and IC₁₀ to ± 5 V.

The display is coupled to K₆ on the generator via K₁. Pin 5 of this connector carries the SYNC signal (which has the same frequency as the output of the MAX038. Unfortunately, there is no possibility of the display showing whether the frequency is in Hz, kHz or MHz. However, a solution to this has been found: if the display shows only digits, the frequency is in Hz; if the digits are separated by a decimal point, the frequency is in kHz, and when the digits are separated by a decimal point and preceded by a colon, the frequency is in MHz.

The time base of the display circuit is provided by IC₇ (note that this must be the A version of the ICM7207). The IC also generates all control signals for the counter proper and display driver IC₈. The combination of these two ICs forms a frequency-independent counter. Depending on the level at pin 11 of IC₇, a measuring period of 0.1 s for the three highest frequency ranges or 1 s for the three lowest ranges is used. This gives measuring cycles of 0.2 s and 2 s respectively. This is too long for the highest frequencies, so that the times are scaled down by 100 and 10 respectively. This is done in IC₆. The final measuring result is displayed on LCD₁.

Power-up network R₃–C₃ arranges for

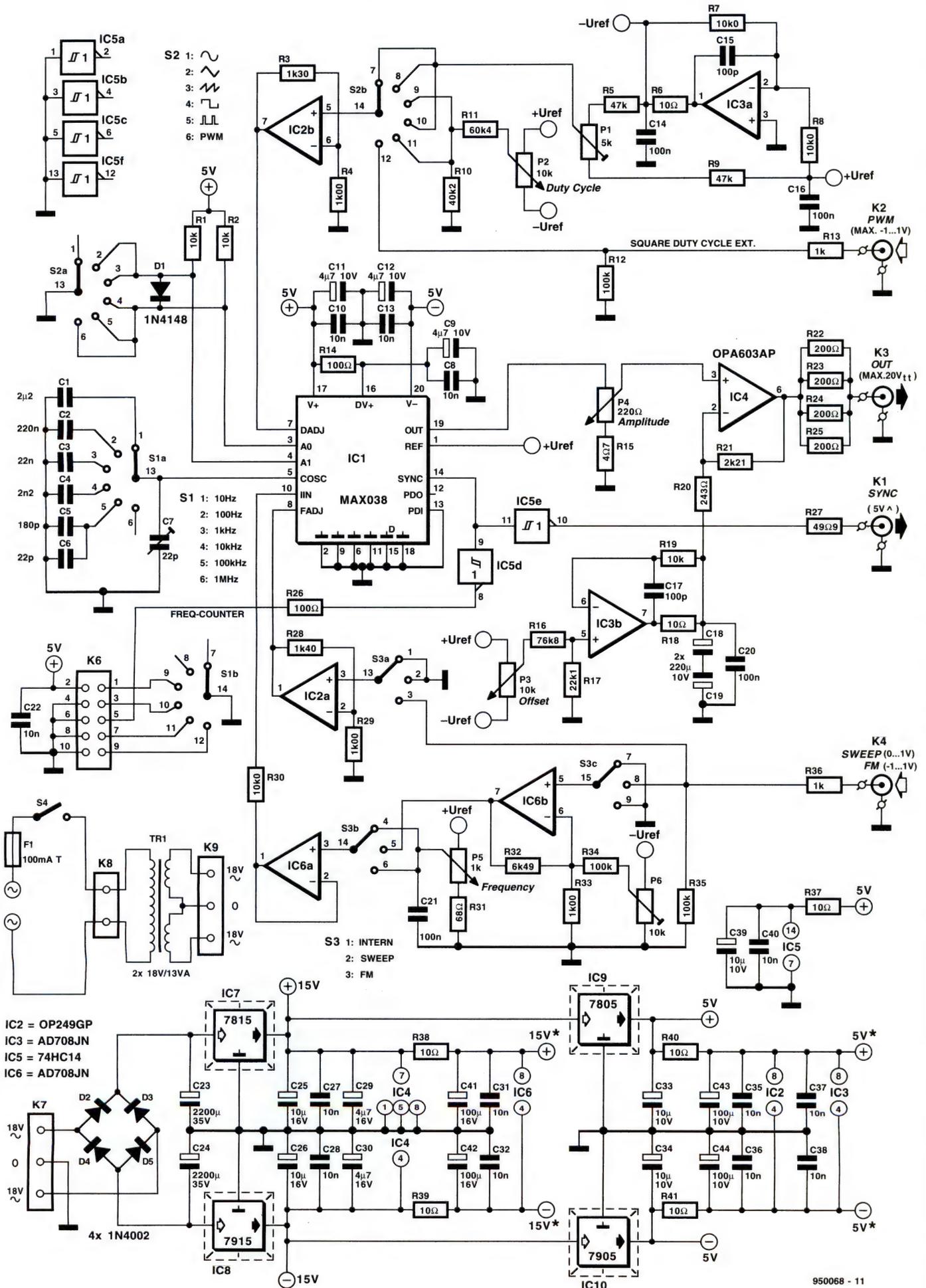


Fig. 1. Circuit diagram of the waveform generator.

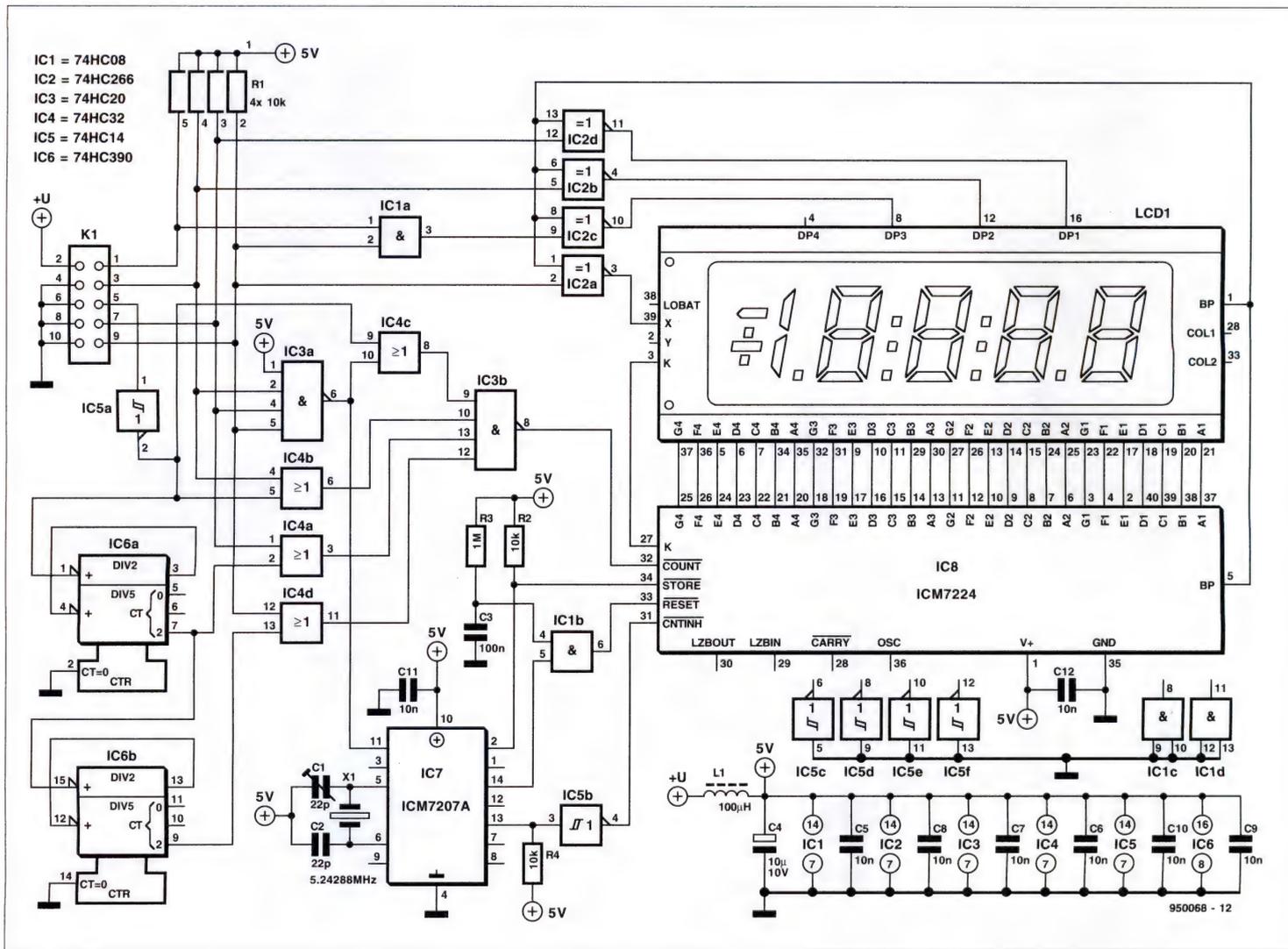


Fig. 2. Circuit diagram of the display unit.

the display to be set to a defined readout after the supply has been switched on. This prevents the appearance of undefined characters on the screen on power up.

The signal at pin 1 (BP) of the LCD ensures that the display is always driven by a.c. Driving it with d.c. would cause irreparable damage.

Construction

The function generator is intended to be built on the double-side, through-plated printed-circuit board shown in Fig. 4. This board consists of three parts, mother board, display board and transformer board, which should be separated from each other before any other work is done.

It is best to start with the mother board: fit four spacers in the fixing holes near the corners—see Fig. 3. Use sockets for all ICs, except IC₁ and IC₄, which should be soldered directly to the board. (Sockets create too much spurious inductance). Note that IC₄ uses the copper pad on the board as heat sink, for which three special pins are provided on the device. Use adequate solder to ensure good thermal coupling with the copper. When the board has been completed, fix a small heat sink on

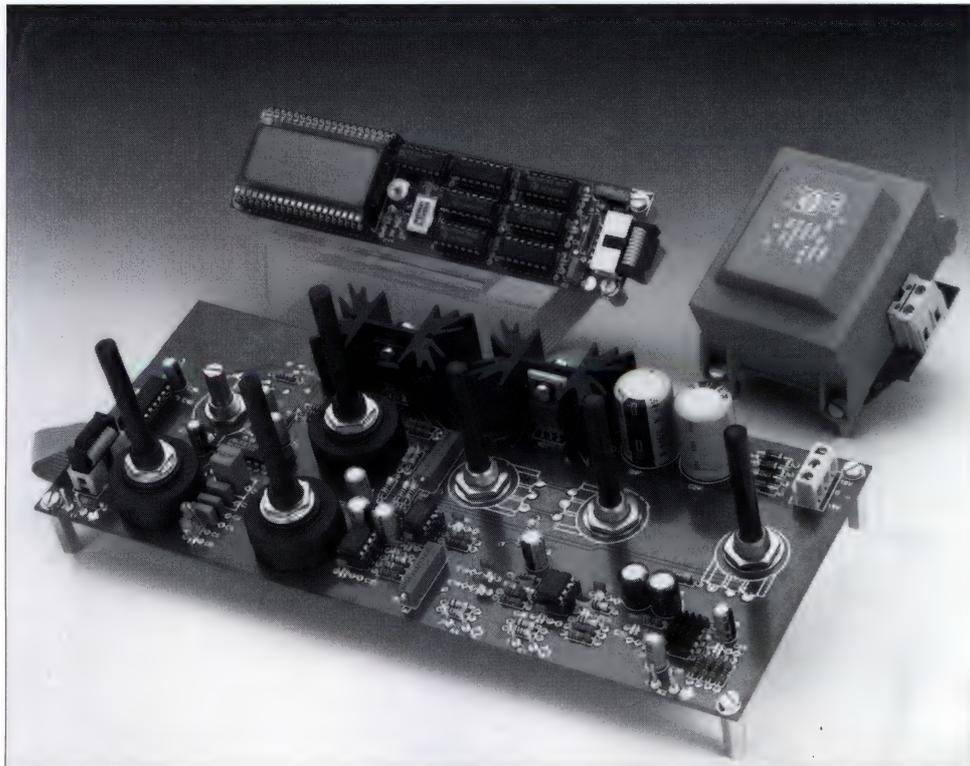


Fig. 3. The three boards that constitute the function generator.

meter.

Assembling the generator

When the generator has been set up and

works correctly, it should be assembled in a suitable enclosure, for instance, as shown in **Fig. 7**. The enclosure should be sturdy and be screened to minimize electromagnetic radiation.

Mount the transformer at the right of the rear panel and the other two boards close behind the front panel. A possible front panel layout is given in **Fig. 8**: note that a ready-made foil for this is available. A photocopy of Fig. 8 can be used as a drilling template for the front panel.

Wiring from the mains entry (with integrated fuse holder) at the rear panel to the mains transformer should be as short as possible and be kept well away from C₁–C₇.

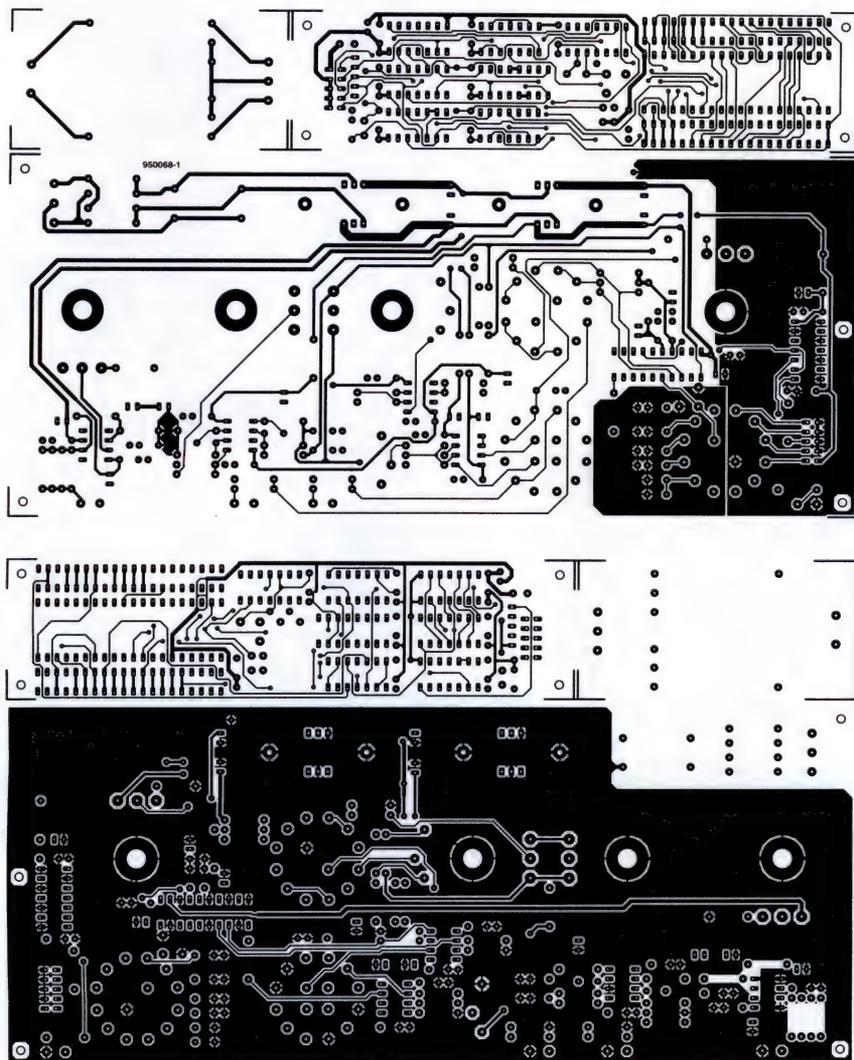


Fig. 4b. Track side and third foil of the PCB (scale 1:2).

Parts list

MOTHER BOARD

Resistors:

- R₁, R₂, R₁₉ = 10 k Ω
- R₃ = 1.30 k Ω *
- R₄, R₂₉, R₃₃ = 1.0 k Ω *
- R₅, R₉ = 47 k Ω
- R₆, R₁₈, R₃₇–R₄₁ = 10 Ω
- R₇, R₈, R₃₀ = 10.0 k Ω *
- R₁₀ = 40.2 k Ω *
- R₁₁ = 60.4 k Ω *
- R₁₂, R₃₄, R₃₅ = 100 k Ω
- R₁₃, R₃₆ = 1 k Ω
- R₁₄, R₂₆ = 100 Ω
- R₁₅ = 4.7 Ω
- R₁₆ = 76.8 k Ω *
- R₁₇ = 22.1 k Ω *
- R₂₀ = 243 Ω *
- R₂₁ = 2.21 k Ω *
- R₂₂–R₂₅ = 200 Ω *
- R₂₇ = 49.9 Ω *
- R₂₈ = 1.40 k Ω *
- R₃₁ = 68 Ω
- R₃₂ = 6.49 k Ω *
- * = 1%

Potentiometers

- P₁ = 5 k Ω (4.7 k Ω) multiturn preset
- P₂, P₃ = 10 k Ω linear
- P₄ = 220 Ω (250 Ω) linear
- P₅ = 1 k Ω multiturn, linear (e.g. Bourns Type 3590S-002-102)
- P₆ = 10 k Ω multiturn preset

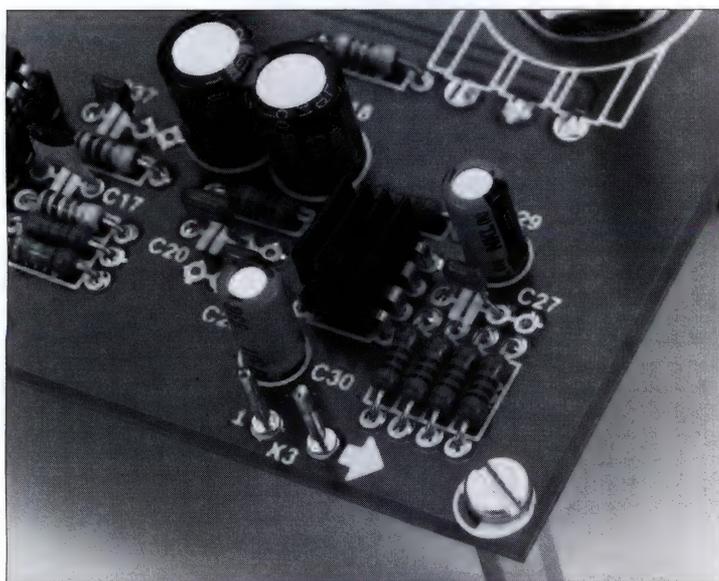


Fig. 5. Detail of how to fix a small heat sink on to IC₄ with a drop of superglue.

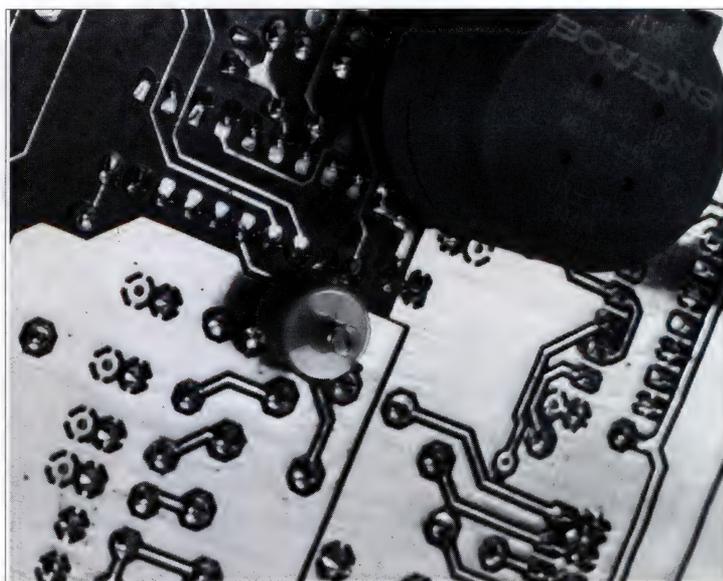


Fig. 6. Detail showing how trimmer C₇ is fitted at the trackside of the mother board.

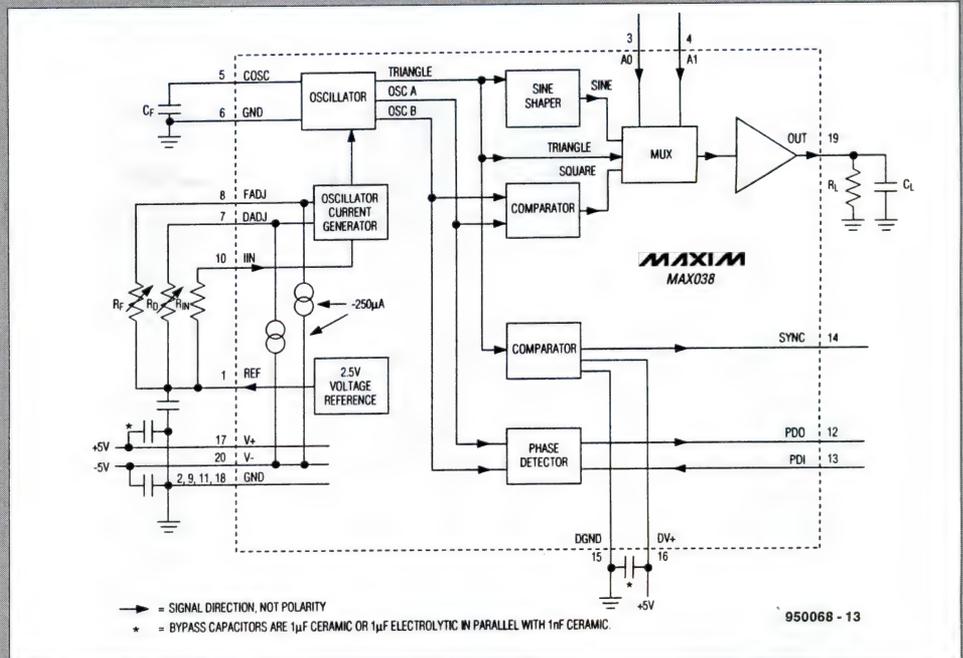
High-frequency waveform generator MAX038

The MAX038 is a high-frequency function generator that produces low-distortion sine, triangle, sawtooth or rectangular (pulse) waveforms at frequencies from less than 1 Hz to 20 MHz or more, using a minimum of external components. Frequency and duty factor can be independently controlled by programming the current, voltage or resistance. The desired output waveform is selected under logic control by setting the appropriate code at the A_0 and A_1 inputs. A SYNC output and phase detector are included to simplify designs requiring tracking to an external signal source.

The MAX038 operates with $\pm 5\text{ V} \pm 5\%$ power supplies. The basic oscillator is a relaxation type that operates by alternately charging and discharging a capacitor, C_F , with constant currents, simultaneously producing a triangle wave and a rectangular wave. The charging and discharge currents are controlled by the current flowing into IIN, and are modulated by the voltages applied to FADJ and DADJ. The current into IIN can be varied from $2\ \mu\text{A}$ to $750\ \mu\text{A}$, producing more than two decades of frequency for any value of C_F . Applying $\pm 2.4\text{ V}$ to FADJ changes the nominal frequency (with $U_{FADJ} = 0\text{ V}$) by $\pm 70\%$; this procedure can be used for fine control.

The duty factor (the percentage of time that the output waveform is positive) can be controlled from 10% to 90% by applying $\pm 2.3\text{ V}$ to DADJ. This voltage changes the C_F charging and discharge current ratio while nearly constant frequency is maintained.

A stable 2.5 V reference voltage, REF, allows simple determination of IIN, FADJ,



or DADJ with fixed resistors, and permits adjustable operation when potentiometers are connected from each of these inputs to REF. FADJ and/or DADJ can be grounded, producing the nominal frequency with a 50% duty factor.

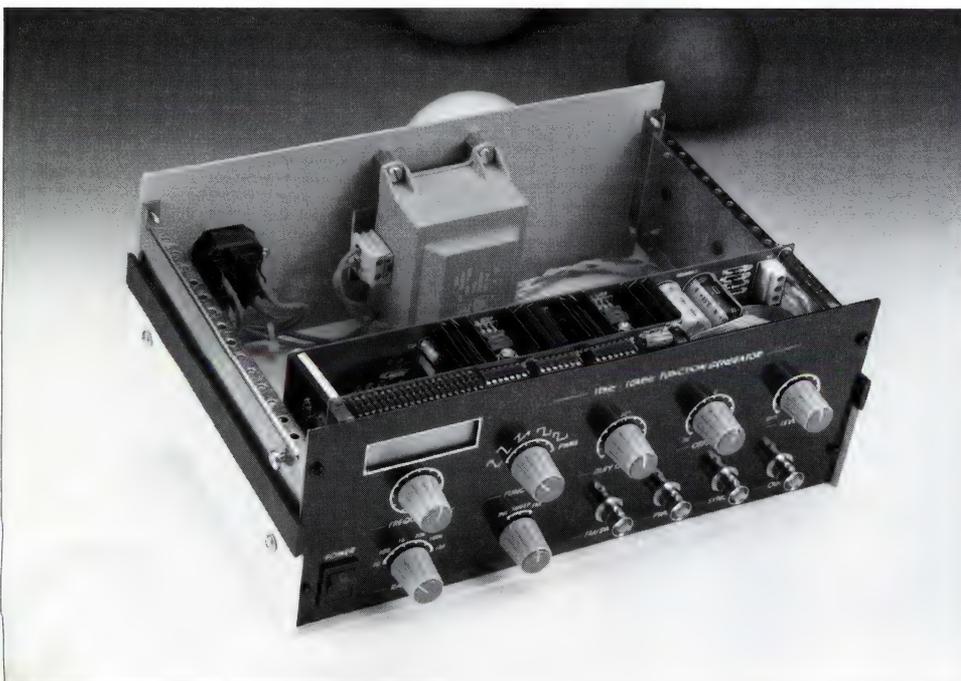
The output frequency is inversely proportional to C_F ; values can be selected for this capacitor to produce frequencies above 20 MHz.

A sine-shaping circuit converts the oscillator triangle wave into a low-distortion sine wave with constant amplitude. The triangle, rectangular and sine waves are input to a multiplexer. Two address lines, A_0 and A_1 , control which of the three waveforms is selected. The output amplifier produces a constant 2 V_{pp}

amplitude ($\pm 1\text{ V}$), regardless of wave shape or frequency.

The triangle is also sent to a comparator that produces a high-speed rectangular-wave SYNC waveform that can be used to synchronize other oscillators. The SYNC circuit has separate power-supply leads and can be disabled.

Two other phase-quadrature rectangular waves are generated in the basic oscillator and sent to one side of an XOR phase detector. The other side of the phase detector input, PDI, can be connected to an external oscillator. The phase detector output, PDO, is a current source that can be connected directly to FADJ to synchronize the MAX038 with the external oscillator.



Capacitors:

- $C_1 = 2.2\ \mu\text{F}$, polypropylene*, 10%
- $C_2 = 220\ \text{nF}$, polypropylene*, 5%
- $C_3 = 22\ \text{nF}$, polypropylene*, 5%
- $C_4 = 2.2\ \text{nF}$, polypropylene*
- $C_5 = 180\ \text{pF}$, polyester, 2%
- $C_6 = 22\ \text{pF}$, polyester, 2%
- $C_7 = 22\ \text{pF}$ foil trimmer
- $C_8, C_{10}, C_{13}, C_{22}, C_{27}, C_{28}, C_{31}, C_{32}, C_{35}-C_{38}, C_{40} = 10\ \text{nF}$
- $C_9, C_{11}, C_{12} = 4.7\ \mu\text{F}$, 10 V, radial
- $C_{14}, C_{16}, C_{20}, C_{21} = 100\ \text{nF}$
- $C_{15}, C_{17} = 100\ \text{pF}$ ceramic
- $C_{18}, C_{19} = 220\ \mu\text{F}$, 10 V, radial
- $C_{23}, C_{24} = 2200\ \mu\text{F}$, 35 V, radial
- $C_{25}, C_{26} = 10\ \mu\text{F}$, 16 V, radial
- $C_{29}, C_{30} = 4.7\ \mu\text{F}$, 16 V, radial
- $C_{33}, C_{34}, C_{39} = 10\ \mu\text{F}$, 10 V, radial
- $C_{41}, C_{42} = 100\ \mu\text{F}$, 16 V, radial
- $C_{43}, C_{44} = 100\ \mu\text{F}$, 10 V, radial

Semiconductors:

- $D_1 = 1\text{N}4148$
- $D_2-D_5 = 1\text{N}4002$

Fig. 7. The completed function generator with top of enclosure removed.

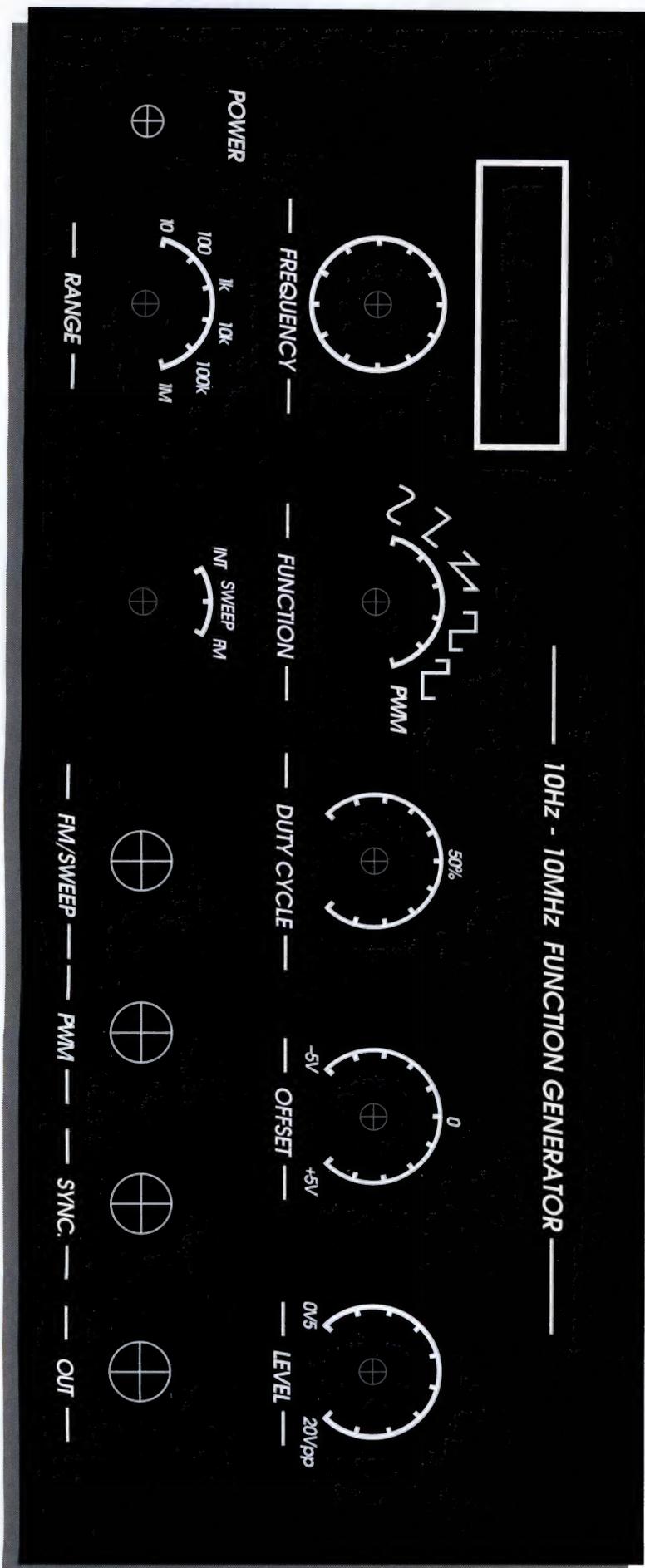


Fig. 8. Suggested front panel layout for the function generator (scale 1:1). A self-adhesive foil is available - see p. 70

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Integrated circuits:

IC₁ = MAX038CPP (Maxim)
 IC₂ = OP249GP (Analog Devices)
 IC₃, IC₆ = AD708JN (Analog Devices)
 IC₄ = OPA603AP (Burr Brown)
 IC₅ = 74HC14
 IC₇ = 7815
 IC₈ = 7915
 IC₉ = 7805
 I₁₀ = 7905

Miscellaneous:

K₁-K₄ = BNC socket (board fitting)
 K₆ = 10-way box header
 K₇, K₉ = 3-way terminal block, 5 mm pitch
 K₈ = 2-way terminal block, 7.5 mm pitch
 S₁, S₂ = 2-pole, 6-position rotary switch
 S₃ = 4-pole, 3-position rotary switch
 S₄ = double-pole on/off switch
 F₁ = fuse, 100 mA, slow
 Tr₁ = mains transformer, secondary
 2 × 18 V, 13 VA
 2 off heat sink, 6.5 KW⁻¹ (e.g. SK129/25*)
 1 off heat sink, 83 K W⁻¹ (e.g. ICK6/8L)
 for DIP-8 case
 4 off ceramic washers
 Screened cable as required
 Enclosure to individual requirements
 (prototype = LC960 from LTP)
 PCB Ref. No. 950068 (see p. 70)
 Front panel foil Ref. No. 950068-F
 (see p. 70)
 * Dau (UK) Ltd, Phone (01243) 553031

DISPLAY BOARD

Resistors:

R₁ = array of 4 × 10 kΩ
 R₂, R₄ = 10 kΩ
 R₃ = 1 MΩ

Capacitors:

C₁ = 22 pF foil trimmer
 C₂ = 22 pF ceramic
 C₃ = 100 nF, polypropylene
 C₄ = 10 μF, 10 V, radial
 C₅-C₁₂ = 10 nF

Inductors:

L₁ = 100 μH

Integrated circuits:

IC₁ = 74HC08
 IC₂ = 74HC266
 IC₃ = 74HC20
 IC₄ = 74HC32
 IC₅ = 74HC14
 IC₆ = 74HC390
 IC₇ = ICM7207A
 IC₈ = ICM7224

Miscellaneous:

K₁ = 10-way box header
 LCD₁ = 4.5 digit liquid crystal display
 (prototype Seiko SP516P)
 X₁ = crystal, 5.24288 MHz
 2 off 10-way socket
 10-core flatcable as required.

[950068]